

Fixed Power Payload Input/Output

College of Engineering



Project Overview

Description: Currently, the Booz Allen's Payload Input Output (PLIO) system serves as a universal translator for third-party sensors. Specifically, the FP PLIO is applied on Booz Allen Hamilton's unmanned surface vehicle (USV), the Man-Portable Tactical Autonomous System (MANTAS). . With the FP PLIO the operators are able to control and utilize the additional systems on the MANTAS, which give them a variety of capabilities such as; setting waypoints, intercept enemy submarines and mines, plant GPS trackers, and strap explosives to enemy ships. It enables the ability to deliver key information to critical military personnel while increasing the safety of personnel as the vehicle is unmanned.

Problem: The most significant issue with the current design of the FP PLIO is the lack of cyber security hardening which impacts the ability to ensure data is distributed to the key decision-makers effectively and efficiently. BAH also looks to utilize the PLIO on a variety of different platforms other than the MANTAS.

Need: Reduce size, weight, power constraints, cost of unit, and redunancy of the original design.



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System Level Diagram



Booz

Manufacturing & Assembly



Heat Sinks Milling Process





Integration

CAD Model on 3D Printing Software

Testing and Evaluation



Gasket and Waterproof Testing



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